J. Lunze: *Graph-Theoretical Methods in Systems Theory and Control*
Edition **MoRa** 2024

Figures that have been produced with MATLAB

22. Dezember 2023

The following table shows figures of the book, which have been produced with MATLAB (Version 2022a). The figure names have been derived from the name of the corresponding MATLAB script.

Figure	Caption	File name
2.26	Result of a depth-first search	`Search2.eps`
2.26	Result of a breadth-first search	`Search3.eps`
2.27	Result of the Dijkstra algorithm for the graph of Fig. 2.16	`Search1.eps`
2.28	Lattice for graph search	`Search5.eps`
6.30	Response of the coupled motors to a step input $u(t) = 115\,\sigma(t)$ with $d_1(t) = d_2(t) = 0$	`IntercMotors2.eps`
6.31	Disturbance behaviour of the coupled motors	`IntercMotors3.eps`
7.28	Attenuation of a step disturbance ($T = 1$, $k_\mathrm{s} = 1$, $k_\mathrm{P} = 0.2$, $k_\mathrm{I} = 0.8$, $x_0 = 0$)	`DistAtten1.eps`
7.30	Attenuation of an oscillating disturbance	`DistAtten2.eps`
7.31	Attenuation of an oscillating disturbance that has a different frequency as the internal model of the controller	`DistAtten3.eps`
7.36	Convergence of the state observation result with precise pendulum model	`UnobservPend2.eps`
7.37	Diverging observation results due to model uncertainties	`UnobservPend3.eps`
7.42	Behaviour of the building for sinusoidal input	`Taipeh1.eps`
7.43	Building behaviour with and without damper	`Taipeh2.eps`
7.44	Comparison of the magnitude plot of the building with and without damper	`Taipeh3.eps`
7.45	Behaviour of the building for the "wrong" wind	`Taipeh6.eps`
9.34	Behaviour of the Markov chain describing a machine tool	`Queue1.eps`
9.35	Behaviour of the machine tool	`Queue2.eps`
9.45	Behaviour of an aperiodic Markov chain	`Stationary1.eps`
9.55	Comparison of the machine tool without control (dashed line) and with feedback controller (solid line)	`Stationary7.eps`
10.20	Binomial distribution (10.39) for $m_\mathrm{max} = 3$ and $p = 0.4$	`RandomGraphs7.eps`

10.21	Binomial distribution (10.39) for $N = 25$	`RandomGraphs1.eps`
10.23	Characteristic path length of random graphs determined numerically for 600 realisations	`RandomGraphs3.eps`
10.24	Diameter of random graphs with the average vertex degree $\bar{d} = 15$ in dependence upon the number N of vertices	`RandomGraphs4.eps`
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11.32	Result of a faulty test	`Dynamometer3.eps`
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12.8	Expected eigenvalue (top) and expected settling time (bottom) in dependence upon the connection probability p of the communication graph	`SyncGMSC4.eps`
12.10	Comparison of the consensus dynamics for systems with three realisations of their random communication graph	`SyncGMSC5.eps`
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12.30	Delay of the robot formation in two experiments with the same connection probability $p = 0.1$	`DelaySelfOrg4.eps`
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A1.1	Breadth-first search of a reachability tree with the root vertex 1	`Search7.eps`
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